



CHAPTER 2

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Unit 7 Automatic Train Operation

- **What is ATO?**
- **Metro Station Stops**
- **Multi-home Signaling-Run In**
- **ATO/ATP Multi-home Signaling**
- **ATO Docking and Starting**

7.1 What is ATO?

- So far, we have only seen how ATP systems work on metros.
 - ◆ ATP is the safety system which ensures that trains remain a safe distance **apart** and have **sufficient warning** to allow them to stop without **colliding with** another train.
- But, ATO (**Automatic Train Operation**) is the non-safety part of train operation related to station stops and starts.

7.1 What is ATO?

- What is ATO? The basic requirement of ATO is to tell the train *approaching a station* where to stop so that the complete train is in the platform.
 - ◆ This is **assuming** that the ATP has **confirmed** that the line is clear.
- The **sequence operates** as show Fig. 7.1 below.

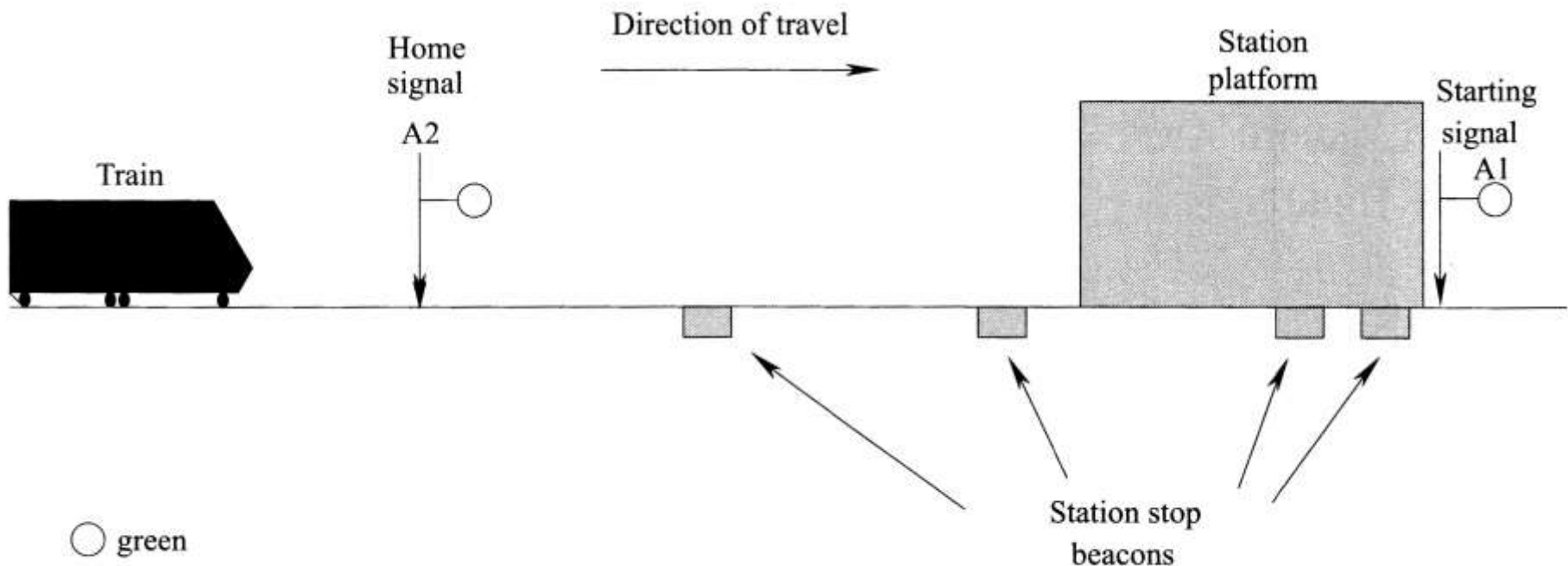


Fig. 7.1 The train approaching a station

7.1 What is ATO?

- The train approaches the station under clear signals so it can do a normal **run in**.
 - ◆ When it reaches the first beacon—originally a **looped cable**, now usually a fixed **transponder**—a station brake **command** is received by the train.
 - ◆ The on board computer calculates the braking curve to enable it to stop at the correct point and, *as the train runs in towards the platform*, the curve is updated a number of times (it varies from system to system) to ensure accuracy.

7.1 What is ATO?

- London's Victoria Line, now 35 years old, has up to 13 “patches” checking the train speed as it **brakes into** a station.
 - ◆ This high number of checks is needed because the onboard braking control gives only three fixed rates of **deceleration**.
 - ◆ Even then, **stopping accuracy** is +2 meters.
- Modern systems require less wayside checking because of the **dynamic** and more accurate on-board braking curve calculations.
 - ◆ Now, modern installations can achieve + 0.15 meters stopping accuracy—**14 times better**.

7.2 Metro Station Stops

- ATO works well when the line is clear and station **run-ins** and **run-outs** are **unimpeded** by the train ahead.
 - ◆ However, ATO has to **be capable of** adapting to **congested** conditions, so it has to **be combined with** ATP at stations when trains are closely following each other.
- Metro operation at stations has always been a particular challenge, and long before ATO appeared in the late 1960s, systems were developed to **minimize the impact** when a train **delayed** too long at a station.

7.2 Metro Station Stops

- To provide a frequent train service on a metro, dwell times at stations must be kept to a minimum.
 - ◆ In spite of the best endeavors of staff, trains sometimes overstay their time at stations, so signaling was developed to reduce the impact on following trains.
 - ◆ To see how this works, we begin with an example (Fig.7.2) of a conventionally signaled station with a starting Signal A1 (green) and a home Signal A2 (red) protecting a train (*Train 1*) standing in the station.
 - ◆ We can assume mechanical ATP (train stops) is provided so the overlap of Signal A2 is a full speed braking distance in advance of the platform.

7.2 Metro Station Stops

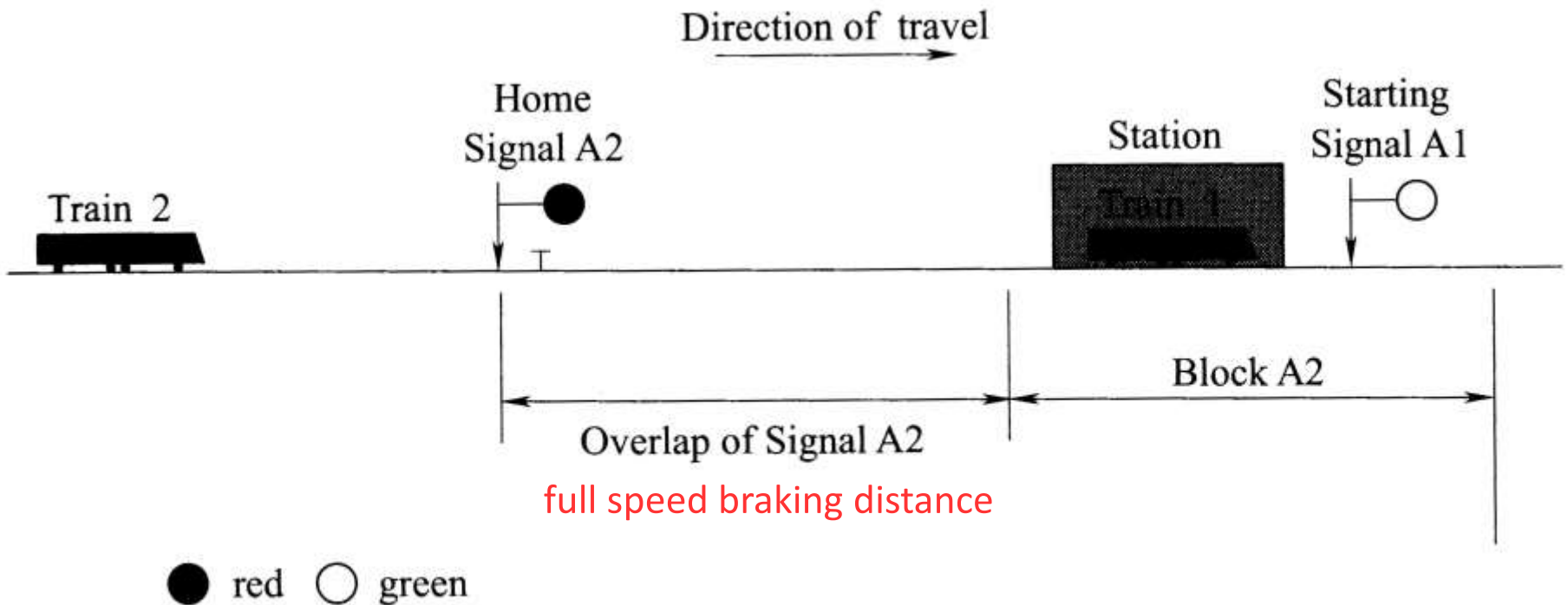


Fig. 7.2 Single-home signaling

7.2 Metro Station Stops

- ◆ As Train 2 approaches, it slows when the driver sees the home Signal A2 **at danger**.
- ◆ Even if Train 1 then **starts and begins to** leave the station, Signal A2 will remain at danger until Train 1 has cleared the overlap of Signal A1.
- ◆ Train 2 will have to stop at A2 but will then restart **almost immediately** when Signal A2 clears. This causes a delay to Train 2 and it requires more energy to restart the train.
- ◆ A way was found to allow the second train to keep moving. It is called **multi-home signaling** (Fig.7.3).

7.2 Metro Station Stops

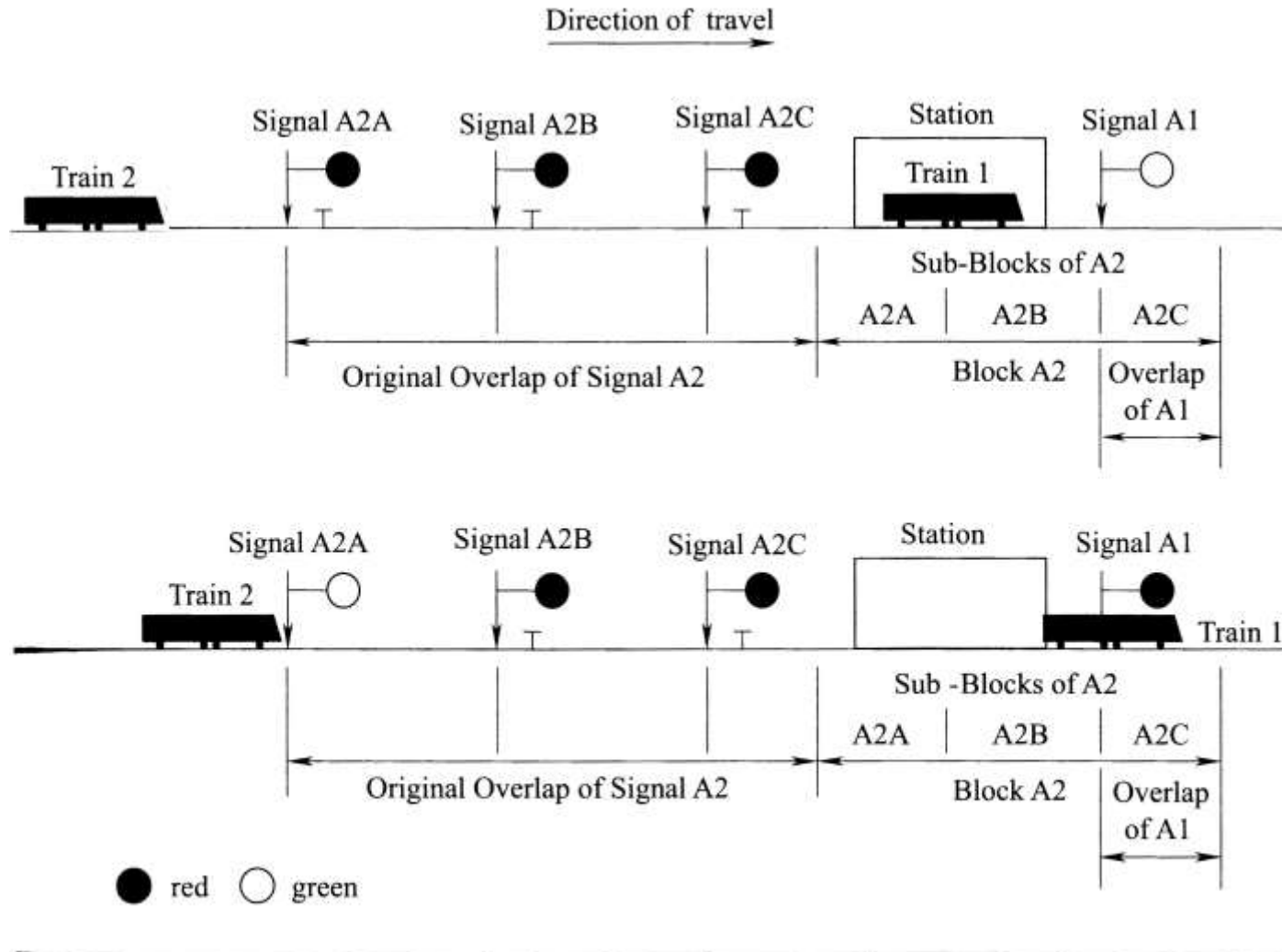


Fig. 7.3 Multi-home signaling system

7.2 Metro Station Stops

- Where multi-home signaling is installed at a station, it **involves** the **provision** of more but shorter blocks, *each with its own signal*.
 - ◆ The **original** home signal in our example has become Signal A2A and, while Train 1 is in the platform, it will remain at danger.
 - ◆ However, Block A2 is **broken up into** three smaller sub-blocks, A2A, A2B, and A2C, *each with its own signal*.
 - ◆ They will also be at danger while Train 1 is in the platform.
 - ◆ Train 2 is approaching and beginning to brake **so as to** stop at Signal A2A.
 - ◆ When Train 1 begins to leave the station, it will clear sub-block A2A first and signal A2A will then show green.
 - ◆ Train 2 will have reduced speed **somewhat** but can now begin its run in towards the platform.

7.3 Multi-home Signaling-Run In

- ◆ At this next stage in the sequence, we can see (Fig.7.4) that Train 1 has now cleared two sub-blocks, A2A and A2B, so two of the multi-home signals are now clear.
- ◆ Note that the starting signal is now red as the train has entered the next block A1.
- ◆ Train 2 is running towards the station at a **reduced speed** but it has not had to stop.
- ◆ When Train 1 clears the overlap of signal A1, the whole of block A2 is clear and signal A2C clears to allow Train 2 an **unobstructed** run into the platform.

7.3 Multi-home Signaling-Run In

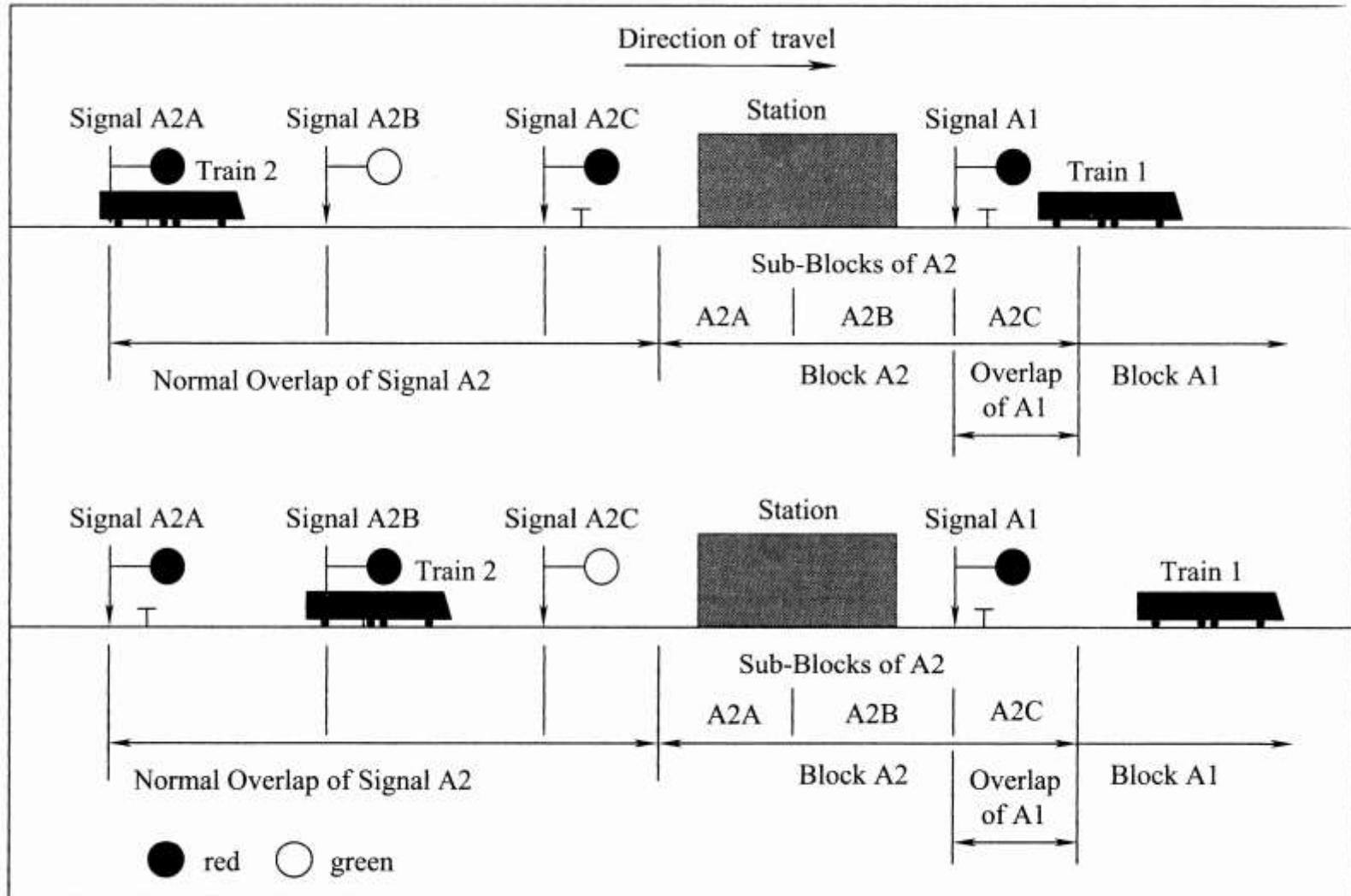


Fig. 7.4 Multi-home signaling—run in

7.4 ATO/ATP Multi-home Signaling

- Fixed block metro systems use multi-home signaling with ATO and ATP.
 - ◆ A series of sub-blocks are provided in the platform area.
 - ◆ These **impose reduced speed braking curves** on the incoming train and allow it to run towards the platform as the **preceding** train departs, **whilst** keeping a safe braking distance between them.
 - ◆ Each curve **represents** a sub-block.
 - ◆ **Enforcement** is **carried out** by the ATP system monitoring the train speed.
 - ◆ The station stop beacons still give the train the data *for the braking curve* for the station stop, but the train will recalculate the curve to **compensate** for the lower speed imposed by the ATP system.

7.5 ATO Docking and Starting

- In addition to providing an automatic station stop, ATO will allow “**docking**” for door operation and restarting from a station.
 - ◆ If a “**driver**”, more often called a “**train operator**” nowadays, is provided, he may be given the job of opening and closing the train doors at a station and restarting the train when all doors are proved closed.
 - ◆ Some systems are designed to prevent doors at a station and restarting the train when all doors are proved closed.
 - ◆ Some systems are designed to prevent doors being opened until the train is “**docked**” in the right place.
 - ◆ Some systems even take door operation away from the operator and give it to the ATO system, so equipment is provided as shown in Fig.7.5.

7.5 ATO Docking and Starting

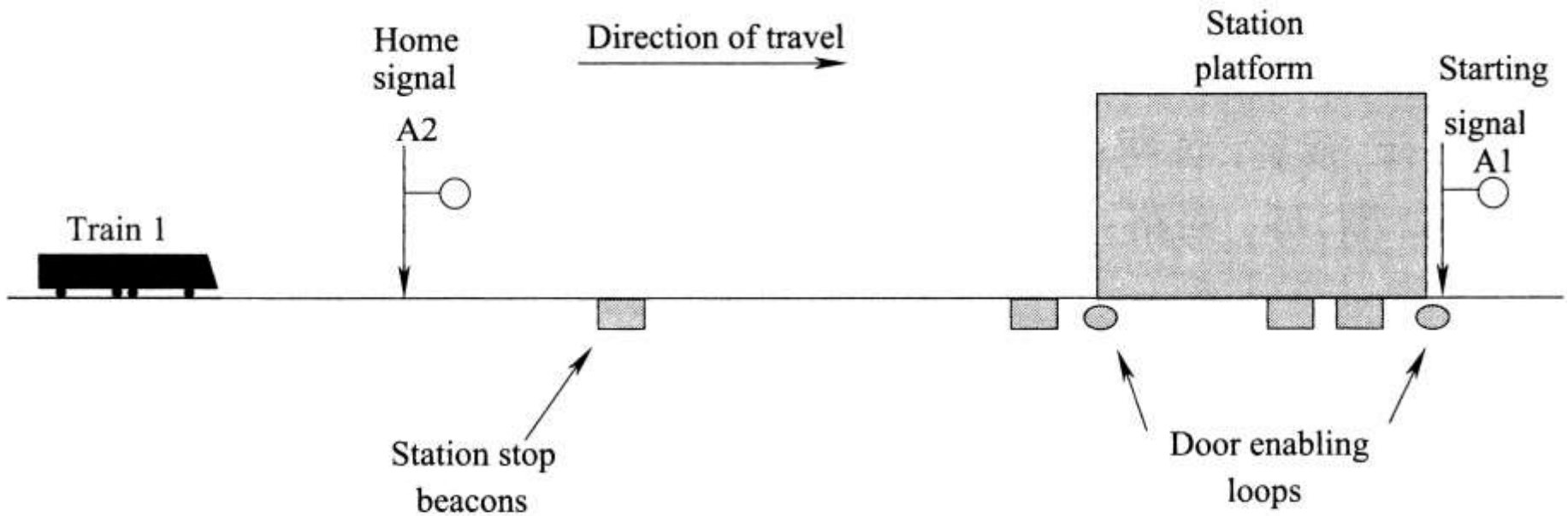


Fig. 7.5 Docking and Starting

7.5 ATO Docking and Starting

- When the train has stopped, it **verifies** that its brakes are applied and checks that it has stopped within the **door enabling loops**.
 - ◆ These loops verify the position of the train **relative to** the platform and which side the doors should open. Once all this is complete, the ATO will open the doors.
 - ◆ After a set time, **predetermined** or **varied** by the control center as required, the ATO will close the doors and automatically restart the train if the **door closed proving circuit** is complete.
- Some systems have platform **screen doors** as well.
 - ◆ ATO will also provide a signal for these to open once it has completed the on-board checking **procedure**.
- Although described here as an ATO **function**, **door enabling** at stations is often incorporated as part of the ATP equipment because it is regarded as a “**vital**” system.

7.5 ATO Docking and Starting

- Once door operation is completed, ATO will then **accelerate** the train to its **cruising speed**, allow it to **coast** to the next station *brake command beacon* and then brake into the next station, assuming no **intervention** by the ATP system.

Homework

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